

# 2D COMPOSITIONAL RESERVOIR SIMULATION USING UNSTRUCTURED GRIDS IN HETEROGENEOUS RESERVOIRS

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**Abstract.** This paper presents a 2D implementation of an element-based finite-volume formulation (EbFVM) using triangles, quadrilaterals, or a combination of both elements in conjunction with a compositional reservoir simulator. The formulation is implemented into the UTCOMP simulator considering a full tensor formulation for the advection and diffusion terms. The UTCOMP simulator was developed at the Center of Petroleum and Geosystems Engineering at The University of Texas at Austin for the simulation of enhanced recovery processes. UTCOMP is a compositional multiphase/multi-component, IMPEC simulator, which can handle the simulation of miscible gas flooding processes. The results of several case studies involving homogeneous and heterogeneous reservoirs are presented in terms of volumetric rates of oil and gas, and saturation fields.

Keywords: EbFVM, Unstructured Meshes, Compositional Reservoir Simulation.

## **1. INTRODUCTION**

Unstructured meshes can handle important features of the reservoirs such as irregular boundaries, sealing faults, discrete fractures, and deviated wells without the utilization of numerical tricks like the inactive blocks commonly used to mimic irregular boundaries, when structured meshes like the conventional Cartesian meshes are employed. Most methodologies that employ unstructured meshes are classified as the control volume finite-element method [4-6], [8-12], [18-19], [21], the finite element method, or the mixed finite element method [7,13-15].

There are some specific differences between the several control volume finite-element methods available in the literature. For instance, the absolute permeabilities and porosities are stored in the vertices of the elements in the approach used by [8-9, 21]. Therefore, in order to perform the flux evaluation, it is necessary to solve a local linear system to guarantee the flux continuity. The authors call the approach multi-point flux approximation. In most CVFEM (Control Volume Finite-Element Method) approaches used in petroleum reservoir simulation, the approximate equations for multiphase fluid flow are obtained first for a single-phase flow and then the transmissibilities are multiplied by mobilities and densities to obtain the equations for the multiphase flow. Fluid flow and heat problems were first solved using the CVFEM in [3] and [20] in conjunction with triangles and quadrilaterals, respectively. The ideas of [3] and [4] were applied to water flooding problems in [4-6]. These authors show that if the equations are obtained from a single-phase flow equation and then transmissibilities are multiplied by densities and phase mobilities, they do not correctly approximate the equations for multiphase flow. They defined their approach as Element based Finite Volume Method (EbFVM). In this work, we will also adopt such a denomination. As explained in [17], we have a methodology that still follows the conservative principles at the discrete level and only borrows the idea of elements and shape functions from the finite element method. Compositional, multiphase, multi-component fluid-flow problems in conjunction with anisotropic and heterogeneous reservoirs were solved by EbFVM using a fully implicit procedure as in [18-19]. In this work, we apply the ideas of EbFVM to an in-house simulator called UTCOMP. UTCOMP was developed at the Center for Petroleum and Geosystems Engineering at The University of Texas at Austin for the simulation of enhanced recovery processes. UTCOMP is an IMPEC (Implicit Pressure Explicit Composition), multiphase/multi-component simulator, which can handle the simulation of several enhanced oil recovery processes [1,2].

#### 2. PHYSICAL MODEL

In this section, we present the formulation for discretization of the partial differential equations arising from the formulation used by the UTCOMP simulator. Then, the procedure to obtain the approximate equations using the EbFVM is presented.

#### 2.1. Component Molar Balance

The material balance in terms of number of moles of each component present in the reservoir is given by

$$\frac{\partial N_i}{\partial t} - \vec{\nabla} \cdot \left[ \sum_{j=1}^{n_p} \xi_j \lambda_j x_{ij} \vec{\vec{k}} \cdot \nabla \Phi_j - \gamma_j \vec{\vec{k}} \cdot \nabla D + \phi \xi_j S_j \vec{\vec{K}}_{ij} \cdot \nabla x_{ij} \right] - \frac{q_i}{V_b} = 0 \text{ for } i = 1, 2, \cdots, n_c, \quad (1)$$

where *D* is the depth, which is assumed to be positive in the downward direction,  $\xi_j$  and  $\lambda_j$  are the molar density and mobility of the *j*-th phase, respectively.  $x_{ij}$  is the molar fraction of

component *i* into phase *j*,  $\gamma_{j}$  is molar weight of phase *j*,  $q_i$  is the molar rate of component *i*, and  $V_b$  is the bulk volume.  $\vec{k}$  and  $\vec{K}_{ij}$  are the absolute permeability and dispersion tensor, respectively. The  $\vec{k}$  and  $\vec{K}_{ij}$  components in Cartesian coordinates are given by

$$\vec{\vec{k}} = \begin{bmatrix} k_{xx} & k_{xy} & k_{xz} \\ k_{xy} & k_{yy} & k_{yz} \\ k_{xz} & k_{yz} & k_{zz} \end{bmatrix}.$$
(2)

$$\vec{\vec{K}}_{ij} = \begin{bmatrix} k_{xx,ij} & k_{xy,ij} & k_{xz,ij} \\ k_{xy,ij} & k_{yy,ij} & k_{yz,ij} \\ k_{xz,ij} & k_{yz,ij} & k_{zz,ij} \end{bmatrix}.$$
(3)

The  $\vec{K}_{ij}$  components are functions of molecular diffusion and mechanical dispersion. The expressions for each one of components can be found in [1].

#### 2.2. Phase-Equilibrium Relationship

The phase-equilibrium calculation determines the number, amounts and composition of all equilibrium phases. The equilibrium solution must satisfy three conditions. First, the molar-balance constraint must be preserved. Second, the chemical potentials for each component must be the same in all phases. Third, the Gibbs free energy at constant temperature and pressure must be a minimum. The first partial derivative of the total Gibbs free energy with respect to the independent variables gives equality of component fugacities among all phases:

$$f_i^{j} - f_i^{r} = 0$$
  $(i = 1, 2, \dots, n_c; j = 1, 2, \dots, N_p - 1).$  (4)

The phase composition constraints

$$\sum_{i=1}^{n_c} x_{ij} - 1 = 0 \quad (j = 1, 2, \cdots, n_p),$$
(5)

and the equations for determining the phase amounts for the two hydrocarbon phases is given by

$$\sum_{i=1}^{n_i} \frac{z_i \left(K_i - 1\right)}{1 + \nu \left(K_i - 1\right)} = 0.$$
(6)

Equations (5)-(6) are implicitly used in the solution of the fugacity equation, Eq. (4), where v is the ratio of moles of gas to total moles.

#### 2.3. Volume Constraint

The volume constraint states that the pore volume in each volume must be filled up completely by the total fluid volume as described below:

$$\sum_{i=1}^{n_c} N_i \sum_{j=1}^{n_p} L_j \overline{v}_j - V_p = 0,$$
(7)

where  $L_j$  is a ratio of moles in phase *j* to the total number of moles in the mixture,  $\overline{v}_j$  is the molar volume of phase *j*, and  $v_p$  is the pore volume.

#### 2.4. Pressure Equation

In the UTCOMP simulator an IMPES approach is used. In this approach, the pressure equation is solved implicitly and conservation equations (Eq. 1) are solved explicitly. The pressure equation is obtained based on the fact that the pore volume should be completely filled by the total volume of fluid:

$$V_t(P,N) = V_p(P), \tag{8}$$

where the total volume of fluid is assumed to be a function of pressure and total number of moles of each component, and the pore volume is related to pressure only. Taking the derivative of the left-hand side of Eq. (8) with respect to pressure and number of moles and the right-hand side with respect to pressure and substituting Eq. (1) in the resulting equation, the following equation for pressure is obtained:

$$\frac{1}{V_{b}} \left( V^{0} c_{f} - \frac{\partial V_{t}}{\partial P} \right) \left( \frac{\partial P}{\partial t} \right) - \sum_{i=1}^{n_{c}+1} \overline{V_{ii}} \vec{\nabla} \bullet \sum_{j=1}^{n_{p}} \vec{k} \lambda_{ij} \xi_{j} x_{ij} \nabla P \\
= \sum_{i=1}^{n_{c}+1} \overline{V_{ii}} \vec{\nabla} \bullet \sum_{j=1}^{n_{p}} \vec{k} \lambda_{ij} \xi_{j} x_{ij} \left( \nabla P_{c2j} - \gamma_{j} \nabla D \right) + \sum_{i=1}^{n_{c}+1} \overline{V_{ii}} \vec{\nabla} \bullet \sum_{j=1}^{n_{p}} \phi \xi_{j} S_{j} \vec{K}_{ij} \bullet \nabla x_{ij} + \frac{1}{V_{b}} \sum_{i=1}^{n_{c}+1} \overline{V_{ii}} q_{i},$$
(9)

where  $\overline{V_{ii}}$  denotes the derivative of total volume of fluid relate to  $N_i$ .

#### **3. APPROXIMATE EQUATIONS FOR UTCOMP USING THE EBFVM**

### **3.1. Material Balance Equation**

In the EbFVM, each element is divided into sub-elements. These sub-elements will be called sub-control volumes. The conservation equation and pressure equation, Eq. (1) and (9), respectively need to be integrated for each one of these sub-control volumes. For a two dimensional discretization there are two possible elements to use (triangular and quadrilateral elements). Figure 1 presents a triangular and a quadrilateral element, and all of the sub-control

volumes associated with each element. Integrating Eq. (1) in time and for each one of the subcontrol volumes, and applying the Gauss theorem for the advective and diffusion terms, we obtain:

$$\int_{V,t} \frac{\partial N_i}{\partial t} dV dt - \int_{A,t} \sum_{j=1}^{n_p} (\xi_j \lambda_j x_{ij} \vec{k} \cdot \nabla \Phi_j + \phi \xi_j S_j \vec{K}_{ij} \cdot \nabla x_{ij}) \cdot d\vec{A} dt - \int_{V,t} \frac{q_i}{V_b} dV dt = 0 \text{ for } i = 1, 2, \cdots, n_c.$$
(10)

To evaluate the first and second terms of Eq. (10), it is necessary to define the shape functions. For triangles and quadrilaterals, linear and bi-linear shape functions as defined through Eqs. (11) and (12), respectively, will be used.

$$N_1(s,t) = 1 - s - t$$
;  $N_2(s,t) = s$ ;  $N_3(s,t) = t$ , (11)

$$N_{1}(s,t) = \frac{1}{4}(1-s)(1-t) ; \quad N_{2}(s,t) = \frac{1}{4}(1+s)(1-t) ;$$

$$N_{3}(s,t) = \frac{1}{4}(1+s)(1+t) ; \quad N_{4}(s,t) = \frac{1}{4}(1-s)(1+t).$$
(12)



Figure 1. Triangular and quadrilateral elements and their respective sub-control volumes.

Using the shape functions, any physical properties or positions can be evaluated inside an element as

$$x(s,t) = \sum_{i=1}^{N_{v}} N_{i} x_{i} ; \quad y(s,t) = \sum_{i=1}^{N_{v}} N_{i} y_{i} ; \quad \Phi_{j}(s,t) = \sum_{i=1}^{N_{v}} N_{i} \Phi_{ji} , \quad (13)$$

where  $N_{\nu}$  denotes the number of vertex for each element. Elements using the same shape function for coordinates and physical properties are known as isoparametric elements [16]. Using the shape functions, gradients of potentials or any other variable can be easily evaluated as

$$\frac{\partial \Phi_j}{\partial x} = \sum_{i=1}^{N_\nu} \frac{\partial N_i}{\partial x} \Phi_{ji} \quad ; \quad \frac{\partial \Phi_j}{\partial y} = \sum_{i=1}^{N_\nu} \frac{\partial N_i}{\partial y} \Phi_{ji} \,. \tag{14}$$

To evaluate the gradients, it is necessary to obtain the derivatives of shape functions relative to x and y. These derivatives are given by

$$\frac{\partial N_i}{\partial x} = \frac{1}{\det(J_i)} \left( \frac{\partial N_i}{\partial s} \frac{\partial y}{\partial t} - \frac{\partial N_i}{\partial t} \frac{\partial y}{\partial s} \right) ; \quad \frac{\partial N_i}{\partial y} = \frac{1}{\det(J_i)} \left( \frac{\partial N_i}{\partial t} \frac{\partial x}{\partial s} - \frac{\partial N_i}{\partial s} \frac{\partial x}{\partial t} \right), \tag{15}$$

where  $J_t$  is the Jacobian matrix of the transformation, and it is given by

$$\det(J_t) = \left(\frac{\partial x}{\partial s}\frac{\partial y}{\partial t} - \frac{\partial x}{\partial t}\frac{\partial y}{\partial s}\right).$$
 (16)

To perform the integral of Eq. (10), it is necessary to define the volumes of each subcontrol volume and the area of each interface. The volumes of each sub-control for triangles and quadrilaterals, respectively, are given by

$$Vscv_i = \frac{\det(J_i)\Delta s\,\Delta t\,h}{6},\tag{17}$$

$$Vscv_i = \det(J_t) \Delta s \Delta t h, \qquad (18)$$

where *h* is the thickness of the reservoir. For a quadrilateral element,  $det(J_t)$  needs to be evaluated at the center of each sub-control volume. The area of each interface, reading counterclockwise, is given by

$$\vec{dA} = h \, dy \, \vec{i} - h \, dx \, \vec{j} \,. \tag{19}$$

Substituting Eqs. (17) and (18) for the accumulation term, and (19) for the advective and diffusive fluxes into Eq. (10), evaluating the fluid properties through an explicit procedure, and dividing each term by the time-step ( $\Delta t$ ) the following equations for the two mentioned terms are obtained:

$$Acc_{m,i} = Vscv_{m,i} \left( \left( \frac{\phi N_m}{\Delta t} \right)_i^{n+1} - \left( \frac{\phi N_m}{\Delta t} \right)_i^n \right) \quad ; \quad m = 1, N_v,$$
(20)

$$F_{m,i} = \int_{A} \sum_{j=1}^{n_p} (\xi_j \, x_{ij} \, \lambda_j \overline{\overline{K}} \bullet \nabla \Phi_j + \phi \xi_j S_j \overline{\overline{K}}_{ij} \bullet \nabla x_{ij}) \bullet \overline{dA}$$
  
$$= \int_{A} \sum_{j=1}^{n_p} (\xi_j \, x_{ij} \, \lambda_j k_{lp})^n \left( \frac{\partial \Phi_j}{\partial x_p} \right)^{n+1} dA_l + \int_{A} \sum_{j=1}^{n_p} \left( \phi \xi_j \, S_j \, k_{ij,lp} \, \frac{\partial x_{ij}}{\partial x_p} \right)^n dA_l \quad ; \qquad (21)$$
  
$$i = 1, n_c + 1 \; ; \quad m = 1, N_v \; ; \; l, \; p = 1, 2.$$

In Equations (20) and (21), the superscript "*n*" and "n+1" means physical properties from the previous time-step and current time-step, respectively. By inspecting Eq. (21), it can be inferred that it is necessary to evaluate molar densities, molar fraction, mobilities, saturations and porosities in two interfaces of each sub-control volume. In the approach used in this work, each element has a constant porosity and absolute permeability tensor, although these properties can change from one element to another. The other physical parameters are based on the vertices of the elements. Therefore, in order to evaluate these properties, an upwind scheme will be used. The mobilities and other fluid properties are evaluated at integration point 1 of Fig. 1a, for instance, by

$$\lambda_{j1,ip1} = \lambda_{j2} \quad if \quad \overline{\overline{K}}.\nabla\Phi_{j}.\overrightarrow{dA}\Big|_{ip1} \le 0$$

$$\lambda_{j1,ip1} = \lambda_{j1} \quad if \quad \overline{\overline{K}}.\nabla\Phi_{j}.\overrightarrow{dA}\Big|_{ip1} > 0.$$
(22)

Inserting Eqs. (20) and (21) into Eq. (10), the following equation for each element is obtained:

$$Acc_{m,i} + F_{m,i} + q_i = 0$$
;  $m = 1, N_v$ ;  $i = 1, n_c + 1.$  (23)

#### **3.2. Pressure Equation**

Integrating Eq. (9) in time and for each one of the sub-control volumes shown in Fig. 1, then applying the Gauss theorem for the advective and diffusion terms, we obtain:

$$\int_{V,t} \frac{1}{V_b} \left( V^0 c_f - \frac{\partial V_t}{\partial P} \right) \left( \frac{\partial P}{\partial t} \right) dV dt - \int_{A,t} \sum_{i=1}^{n_c+1} \overline{V_{ii}} \sum_{j=1}^{n_p} \lambda_{ij} \xi_j x_{ij} \vec{k} \bullet \nabla P \bullet d\vec{A} dt$$

$$= \int_{A,t} \sum_{i=1}^{n_c+1} \overline{V_{ii}} \sum_{j=1}^{n_p} \lambda_{ij} \xi_j x_{ij} \vec{k} \bullet \left( \nabla P_{c2j} - \gamma_j \nabla D \right) \bullet d\vec{A} dt + \int_{A,t} \sum_{i=1}^{n_c+1} \overline{V_{ii}} \sum_{j=1}^{n_p} \phi \xi_j S_j \vec{K}_{ij} \bullet \nabla x_{ij} \bullet d\vec{A} dt + (24)$$

$$\int_{V,t} \frac{1}{V_b} \sum_{i=1}^{n_c+1} \overline{V_{ii}} q_i dV dt.$$

Substituting Eq. (19) for the advective and diffusive fluxes into Eq. (24) and evaluating the fluid properties in each interface of the sub-control volumes through an explicit procedure, the following equation for pressure is rendered for the accumulation, advective and diffusive, and sink/source terms:

$$Accp_{m} + F_{m} + B_{m} = 0$$
;  $m = 1, N_{v}$ , (25)

where  $A_{ccp,m}$ ,  $F_m$ , and  $B_m$  denote the accumulation, advective and diffusive, and sink/source terms, respectively. The approximate expressions for each one of these terms are given below:

$$Accp_{m} = \left( \left( V_{m}^{o}C_{f} \right) - \left( \frac{\partial V_{t}}{\partial P} \right)_{m}^{n} \right) \left( P_{m}^{n+1} - P_{m}^{n} \right) \quad ; \quad m = 1, N_{v} , \qquad (26)$$

$$F_{m} = -\int_{A,t} \sum_{i=1}^{n_{c}+1} \overline{V}_{ii} \sum_{j=1}^{n_{p}} \lambda_{rj} \xi_{j} x_{ij} \vec{k} \bullet \nabla P \bullet d\vec{A} dt - \int_{A,t} \sum_{i=1}^{n_{c}+1} \overline{V}_{ii} \sum_{j=1}^{n_{p}} \lambda_{rj} \xi_{j} x_{ij} \vec{k} \bullet \left(\nabla P_{c2j} - \gamma_{j} \nabla D\right) \bullet d\vec{A} dt - \int_{A,t} \sum_{i=1}^{n_{c}+1} \overline{V}_{ii} \sum_{j=1}^{n_{c}+1} \overline{V}_{ii} \sum_{j=1}^{n_{c}+1} \overline{V}_{ii} \sum_{j=1}^{n_{c}+1} \overline{V}_{ii} \sum_{j=1}^{n_{c}} \left(\lambda_{rj} \xi_{j} x_{ij}\right)_{ip}^{n} k_{ql} \Delta t \frac{\partial P}{\partial x_{l}} dA_{q}$$

$$-\sum_{i=1}^{n_{c}+1} \overline{V}_{ii} \sum_{j=1}^{n_{p}} \left(\lambda_{rj} \xi_{j} x_{ij}\right)_{ip}^{n} \Delta t k_{ql} \left(\frac{\partial P_{c2j}}{\partial x_{l}} - \gamma_{j} \frac{\partial D}{\partial x_{l}}\right) - \sum_{i=1}^{n_{c}+1} \overline{V}_{ii} \sum_{j=1}^{n_{p}} \left(\phi \xi_{j} S_{j}\right)_{ip}^{n} \Delta t k_{ij,ql} \frac{\partial x_{ij}^{n}}{\partial x_{l}} dA_{q}$$

$$m=1, N_{v}; q, l=1, 2,$$

$$n \neq 1$$

$$B_m = \Delta t \sum_{j=1}^{n_c+1} \overline{V}_{ii} q_i \quad ; \quad m = 1, N_v .$$
(28)

Equations (23) and (25) denote the molar conservation of *i-th* component and the approximate equation for the evaluation of pressure field, for each sub-element. Now, it is necessary to assemble the equation of each control volume obtaining the contribution of each sub-control volume that shares the same vertex. This process is similar to the assembling of the stiffness global matrix in the finite element method. Figure 2 presents a control-volume around vertex 5 (dark continuous lines) that will receive contributions from scv1 of element 1, scv3 of element 2, scv4 of element 6, and svc1 of element 7. It is important to mention that each control-volume equation can have different permeabilities and porosities.



Figure 2. Control volume.

### 4. RESULTS AND DISCUSSION

In this section, we will present the three cases studies in conjunction with the EbFVM formulation. The first case refers to a three component gas injection in a quarter-of-five-spot configuration considering an isotropic and homogeneous reservoir. All reservoir data used for this case are shown in Table 1. The Corey's model relative permeabilities parameters are presented in Table 2.

Table 1. Input data – Case 1.			
Reservoir data	Initial conditions	Physical properties and	
		well conditions	
Reservoir dimension (Lx =	Water saturation $= 0.17$	Water viscosity = $1cP$	
Ly = 170.69m and $Lz =$		$(1 \times 10^{-3} \text{ Pa.s})$	
30.48m)			
Absolute permeability (Kxx	Reservoir pressure $= 500$ psi	Gas injection rate =	
$=$ Kyy) $= 10$ mD ( $1.0$ x $10^{-14}$	(3.45 MPa)	$0.1639 \text{ m}^3/\text{s}$	
m²)			
Porosity $= 0.35$	Overall fraction of hydrocarbon	Producer's bottom hole	
	components (C1, C3, C10) = $0.3$ ,	pressure = 500psi (3.45	
	0.3, 0.4	MPa)	

Table 2. Relative	permeability parameters -	Case	1.
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	Water	Oil	Gas
End point relative permeability	1.0	1.0	1.0
Residual saturation	0.2	0.1	0.1
Exponent of relative permeability	1.0	1.0	1.0

One of the unstructured meshes used in this case is shown in Figure 3, where the blue and red spots are the injection and production wells, respectively.



Figure 3: Unstructured hybrid mesh with 1407 nodes – Case 1.

The oil and gas production rates curves are shown in Figure 4 and Figure 5, respectively. From these figures, a good agreement can be verified between the unstructured investigated meshes and the refined Cartesian mesh. It is also important to mention that the number of volumes used by the unstructured grids in order to obtain the same accuracy as the refined Cartesian mesh (100x100) is much smaller.



The gas saturation field at 500 days obtained with the hybrid and refined Cartesian mesh are presented in Figure 6. Although the hybrid mesh is much more coarse than the Cartesian one, we can observe a good agreement in the gas saturation front.



Figure 6. Gas saturation at 500 days. (a) Cartesian mesh (b) Hybrid mesh.

The second case refers to a six component injection in a quarter-of-five-spot configuration, but now the effect of the dispersion terms into the conservation equations were taken into account. The reservoir data, longitudinal and transversal dispersion coefficients and the component data set are presented in Table 3. Table 4 shows the molecular diffusion of the components in each phase. Figure 7 7 shows the unstructured meshes employed for Case 2.

Table 3. Input data – Case 2.				
Reservoir data	Initial conditions	Physical properties and well		
		conditions		
Reservoir dimension (Lx = Ly = 170.7 m, Lz = 30.5 m) Absolute permeability (Kxx= Kyy) = 1,000mD $(10^{-12} m^2)$ Porosity = 0.35 Longitudinal dispersivity = 4.74 m Transversal dispersivity = 4.74 m Longitudinal and transverse parameter for Young's dispersion model = 0.91 m Limit on effective longitudinal and transverse dispersivity for Young's model = 1.9 m	Water saturation $S_{wi} = 0.17$ Reservoir pressure = 500 psi (3.45 MPa) Overall fraction of hydrocarbon components (C <sub>1</sub> , C <sub>3</sub> , C <sub>6</sub> , C <sub>10</sub> , C <sub>15</sub> , C <sub>25</sub> )= 0.5, 0.03, 0.07, 0.2, 0.15, 0.05	Water viscosity = 1 cP $(1x10^{-3} Pa.s)$ Gas injection rate = $0.1639 \text{ m}^3/\text{s}$ Producer's bottom hole pressure = 500psi (3.45 MPa) Injected fluid composition (C1, C3, C6, C10, C15, C25) = 0.77, 0.2, 0.01, 0.01, 0.005, 0.005		

Table 4. Molecular diffusion values – Case 2.

Component	Water	Oil	Gas
C1	0.00	5.0	0.00
C3	0.00	3.0	0.00
C6	0.00	1.0	0.00
C10	0.00	0.5	0.00
C15	0.00	0.0	0.00
C25	0.00	0.0	0.00
		**********	



Figure 7. Triangular unstructured grids – (a) 1701 nodes (b) 3638 nodes

Figures 8 and 9 present the volumetric rates of oil and gas at standard surface, respectively. From these figures, it can be seen that a good agreement between the results obtained with the two unstructured and the two Cartesian meshes. The main goal of this case study was to verify the implementation of the dispersion tensor for unstructured meshes. It is worthwhile to mention that each element has a constant dispersion tensor; therefore, no interpolation is necessary to evaluate the dispersion fluxes along each integration point. Figure 10 shows the oil saturation field in two simulated times. Also the results for the more refined Cartesian mesh are presented. Once again, it is possible to verify a good agreement between the results produced by the two different approaches.



Figure 8. Oil production rate – Case 2.



Figure 9. Gas production rate – Case 2.



Figure 10. Oil saturation. Left triangular mesh -3638 Volumes; right – Cartesian (80x80). a) 500 days b) 1800 days.

The third case refers to the injection of immiscible gas in a saturated reservoir with irregular borders. Figure 11 presents one the employed meshes as well the position of the four wells (two injectors and two producers). The reservoir data, components initial composition and fluid injection composition are shown in Table 5, and Stone's 2 model are shown in Table 6.



Figure 11. Reservoir with mixed mesh – Case 3.

Table 5. Input data.			
Reservoir data	Initial conditions	Physical properties and well	
		conditions	
Reservoir's area =	Water saturation $S_{wi} = 0.25$	Water viscosity = $1 \text{ cP} (1 \times 10^{-1} \text{ cP})$	
4258528 m <sup>2</sup>	Reservoir pressure = 3,000 psi	<sup>3</sup> Pa.s)	
Reservoir's thickness	(20.7 MPa)	Gas injection rate =	
= 152.4 m	Overall fraction of hydrocarbon	$0.1639 \text{ m}^3/\text{s}$	
Absolute permeability	components ( $C_1$ , $C_3$ , $C_6$ , $C_{10}$ , $C_{15}$ ,	Producer's bottom hole	
$(K_{xx} = K_{yy}) = 100 \text{ mD}$	$C_{25} = 0.5, 0.03, 0.07, 0.2, 0.15, 0.05$	pressure = 3,000psi (20.7	
$(10^{-13} \text{ m}^2)$	23, , , , , , , ,	MPa)	
Porosity = 0.3		Injected fluid composition	
101051ty = 0.5		(C1, C3, C6, C10, C15, C25)	
		= 0.8, 0.2, 0.0, 0.0, 0.00, 0.00	

Table 6. Parameters for Stone's 2 model – Case 3.				
	Water	Oil/Water	Oil/Gas	Gas
End point relative permeability	0.3	1.0	1.0	1.0
Residual saturation	0.2	$10^{-6}$	$10^{-6}$	0.0
Exponent of relative permeability	1.0	1.0	1.0	1.0

Due to the difficulty in adjusting a Cartesian mesh to the irregular shape of the reservoir, the results for this case are not presented for Cartesian meshes. Figures 12 through 14 present the total oil and gas rates at standard surfaces, respectively, and the average reservoir pressure. From these figures, a good agreement can be observed between all the reported results.



Figure 12. Oil production rate – Case 3.



Figure 13. Gas production rate – Case 3.



Figure 14. Average reservoir pressure – Case 3.

The overall composition of component 1 at three simulation times are present in Figure 15. From this figure, it can be verified that a good resolution front of the injected  $C_1$  component was obtained.



Figure 15. Overall composition of injected c1 component. a) 0 days b) 248 days c) 977 days d) 1974 days.

## **5. CONCLUSIONS**

The implementation of an EbFVM in conjunction with unstructured grids considering the advection and diffusion transport terms into the UTCOMP simulator were carried out in this work. The results of select case studies were compared to the original formulation of the UTCOMP simulator using Cartesian meshes and a very good agreement between the results were obtained.

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